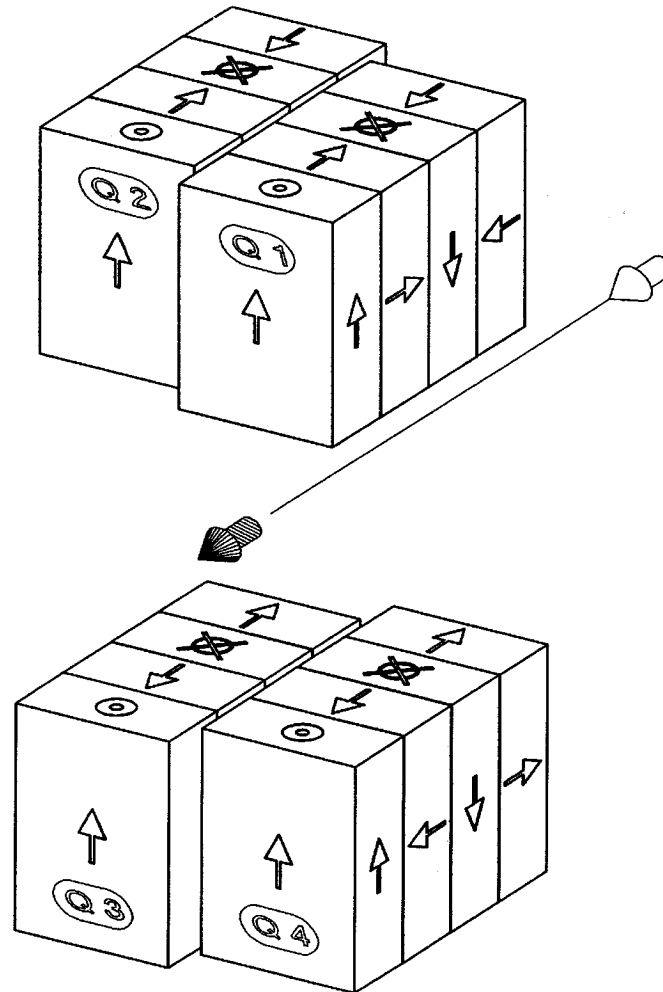


Magnetic Performance of the Advanced Light Source EPU5.0 Elliptically Polarizing Wiggler

**S. Marks, J. DeVries, E. Hoyer, B. M. Kincaid,
D. Plate, P. Pipersky, R. Schlueter, A. Young**

W. Gath, T. Aikens, D. Anderson

EPU Principal of Operation



EPU Principal of Operation



- Four Identical Quadrants
- Polarization Changes by Moving Q1/Q3 Relative to Q2/Q4

$$B_x = B_{x0} \sin(\varphi/2); \quad B_y = B_{y0} \cos(\varphi/2); \quad \varphi = 2\pi dz / \lambda$$

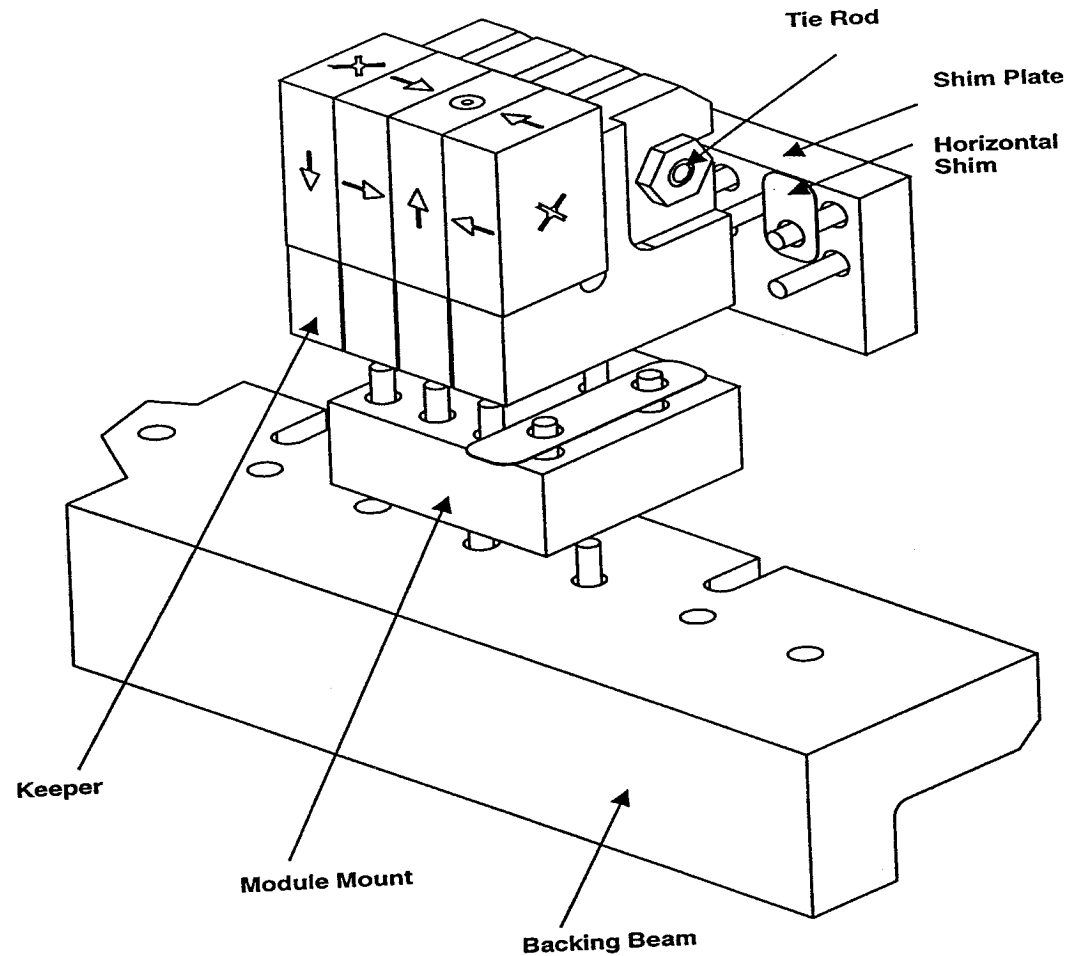
- Polarization Modes
 - horizontal: $dz = 0$, $B_{x0} = 0$
 - vertical: $dz = \lambda/2$, $B_{y0} = 0$
 - circular: $B_x = B_y$, fundamental only
 - elliptical: $B_x \neq B_y$, harmonics

Magnetic Design

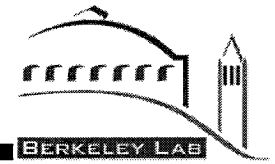


- **5.0 cm Period Length**
- **Standard Sasaki Configuration**
- **13.8 mm Minimum Gap**
- **37.5 Full Strength Periods**
- **Magnetic Modules Consist of 4 Keepers**
- **Each Keeper is Adjustable ± 0.25 mm in x and y**
- **Ends Designed to be Steering & Deflection Free**

EPU Magnetic Module



EPU5.0 Design Spectrum



$$B_r = 1.2 \text{ T}$$

$$G_{\min} = 14.5 \text{ mm}$$

$$B_y = 3B_x \text{ (elliptical)}$$

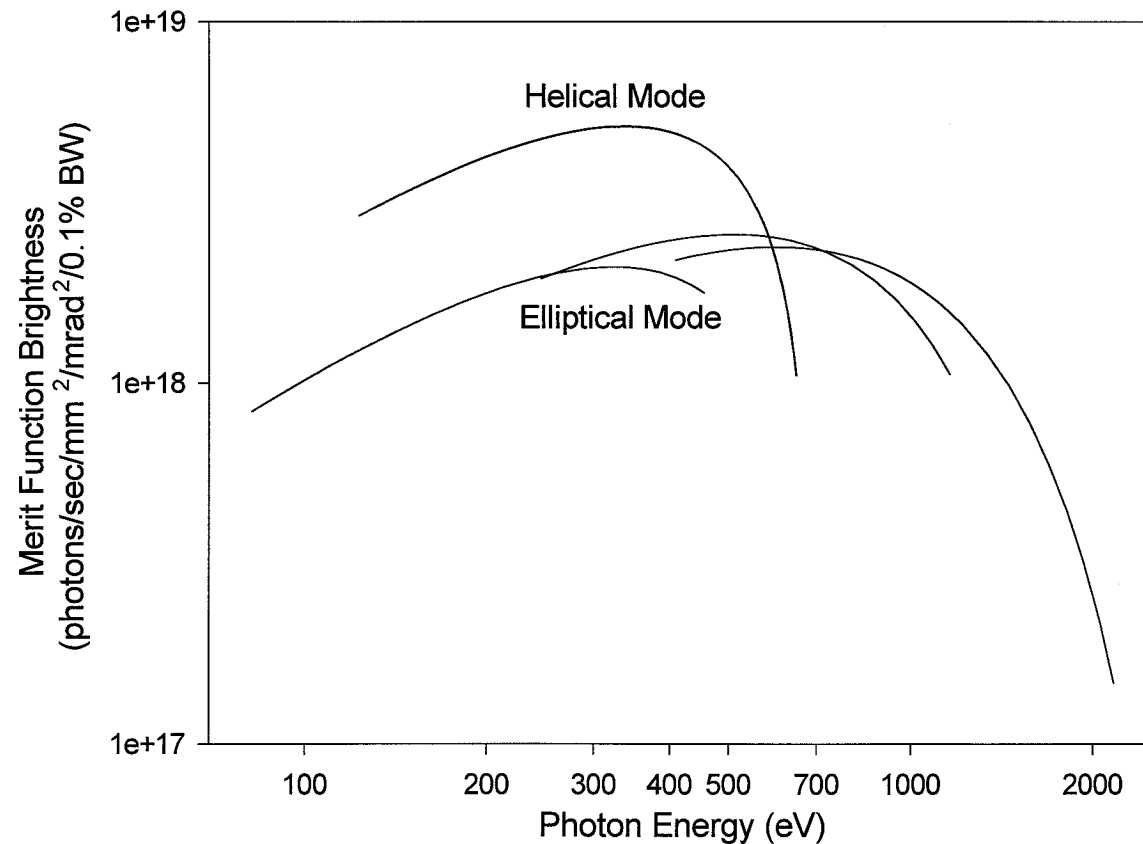
$$P_c > 0.75$$

Elliptical:

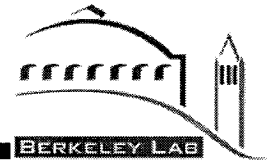
100eV - 1500eV

Helical:

130eV - 500eV

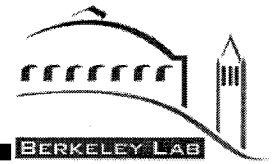


Magnetic Shimming



- **Approaches for conventional undulators:**
 - **Limit RMS field errors: tolerances, shimming**
 - **Apply iron shims to cancel accumulated errors, determined from field measurements**
- **Approach for EPU5.0:**
 - **Measure fields and determine errors for $dz = 0$ and $dz = \lambda/2$**
 - **Minimize local phase errors, local field integrals with dx, dy for Q1/Q3 and Q2/Q4**
 - **Minimize lateral integral nonuniformities**
 - **Check spectrum for other φ**

Optical Phase Error



$$\begin{aligned}\Delta s(z) = & x_0(z)\Delta x'(z) + y_0(z)\Delta y'(z) \\ & - \int_{-\infty}^z [x_0(\xi)\Delta x''(\xi) + y_0(\xi)\Delta y''(\xi)]d\xi \\ & + \frac{1}{2} \int_{-\infty}^z [\Delta x'^2(\xi) + \Delta y'^2(\xi)]d\xi\end{aligned}$$

Results of Shimming

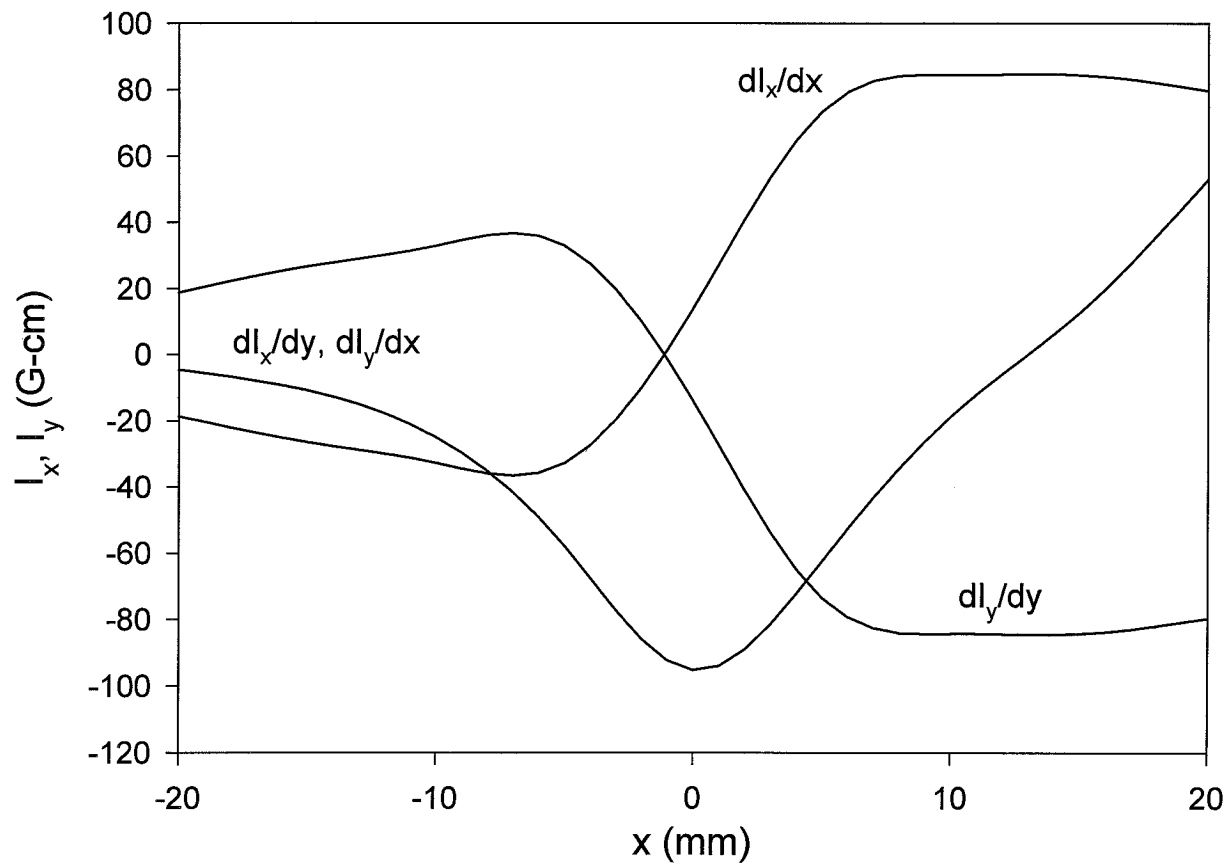


- **Three Shimming Iterations**
- **$dz = 0$:**
 - **RMS Phase error: $10^\circ \Rightarrow 9^\circ$**
 - **RMS I_x : 147 G-cm $\Rightarrow$ 59 G-cm**
 - **RMS I_y : 95 G-cm $\Rightarrow$ 76 G-cm**
- **$dz = \lambda/2$:**
 - **RMS Phase error: $32^\circ \Rightarrow 12^\circ$**
 - **RMS I_x : 218 G-cm $\Rightarrow$ 56 G-cm**
 - **RMS I_y : 165 G-cm $\Rightarrow$ 64 G-cm**

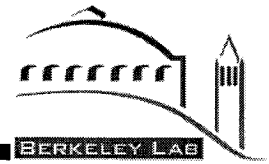
Integral Distribution Shimming



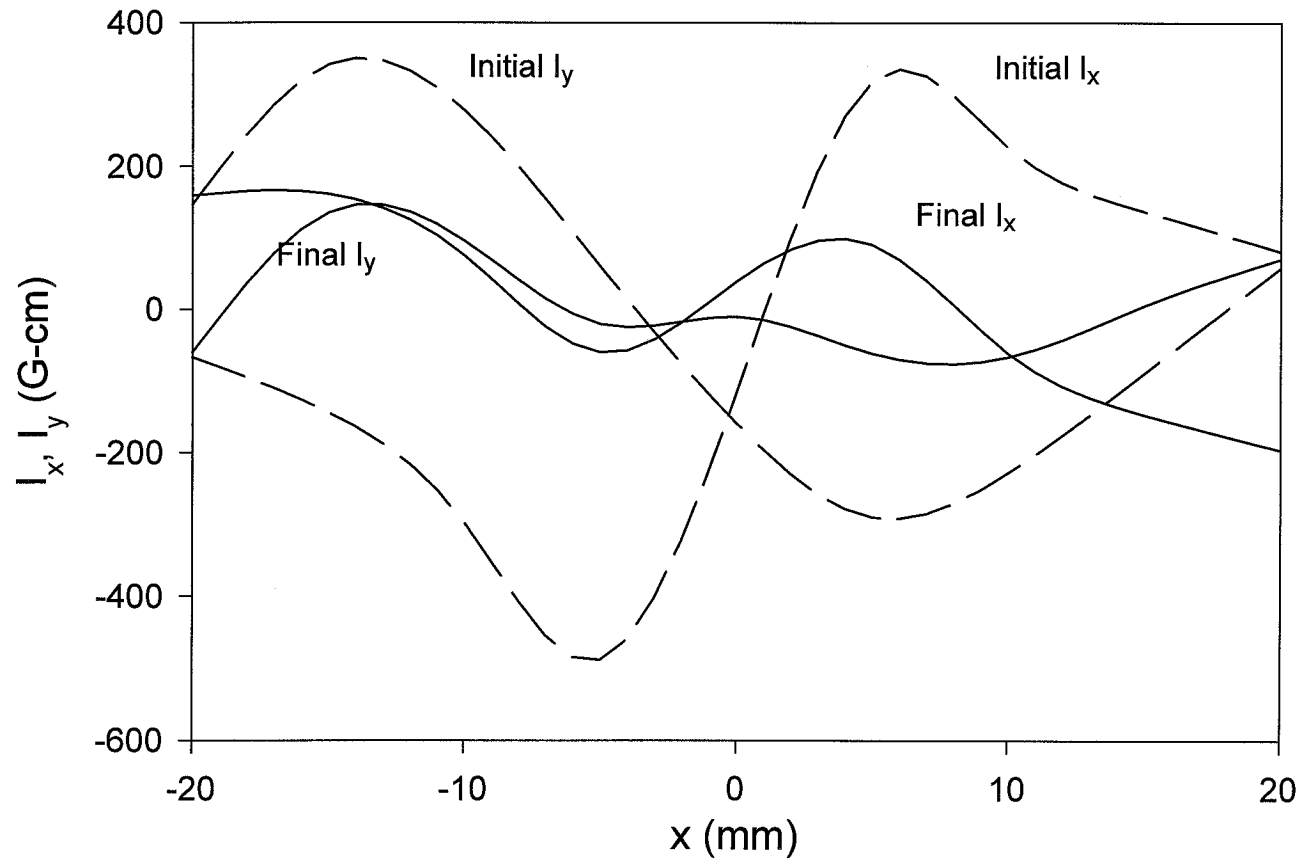
Change in I_x and I_y due to $dx, dy = 0.25$ mm



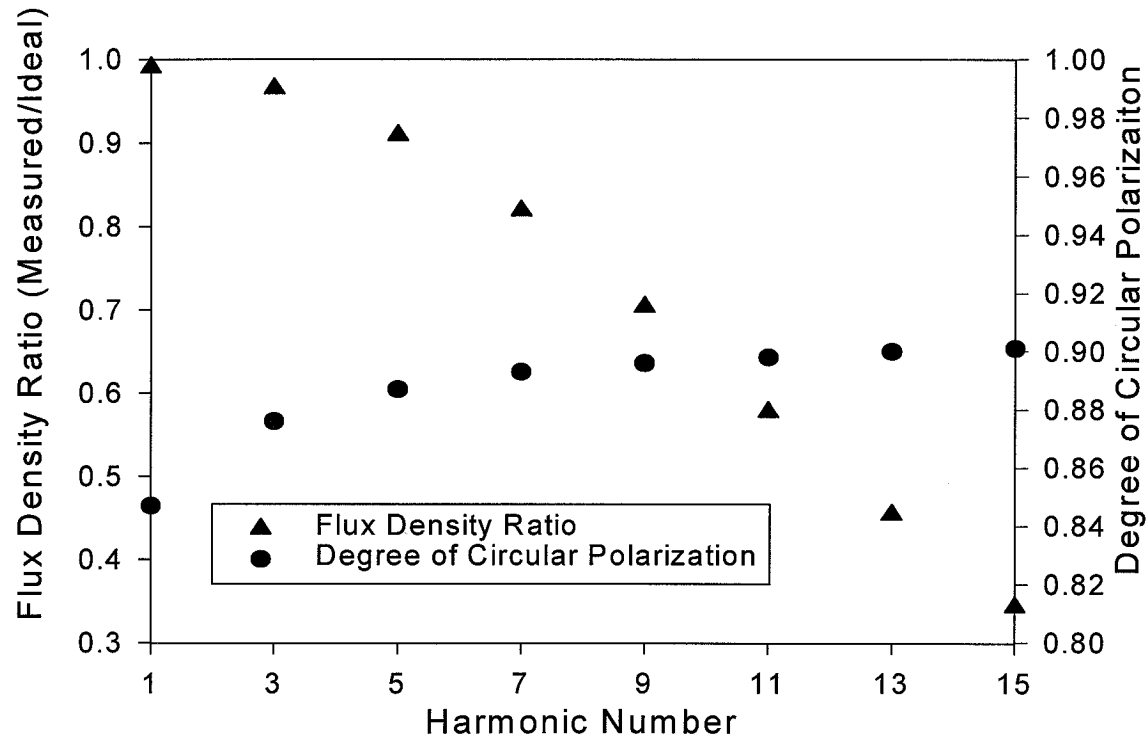
Results of Integral Shimming



I_x and I_y at 14 mm gap, $dz = 0$



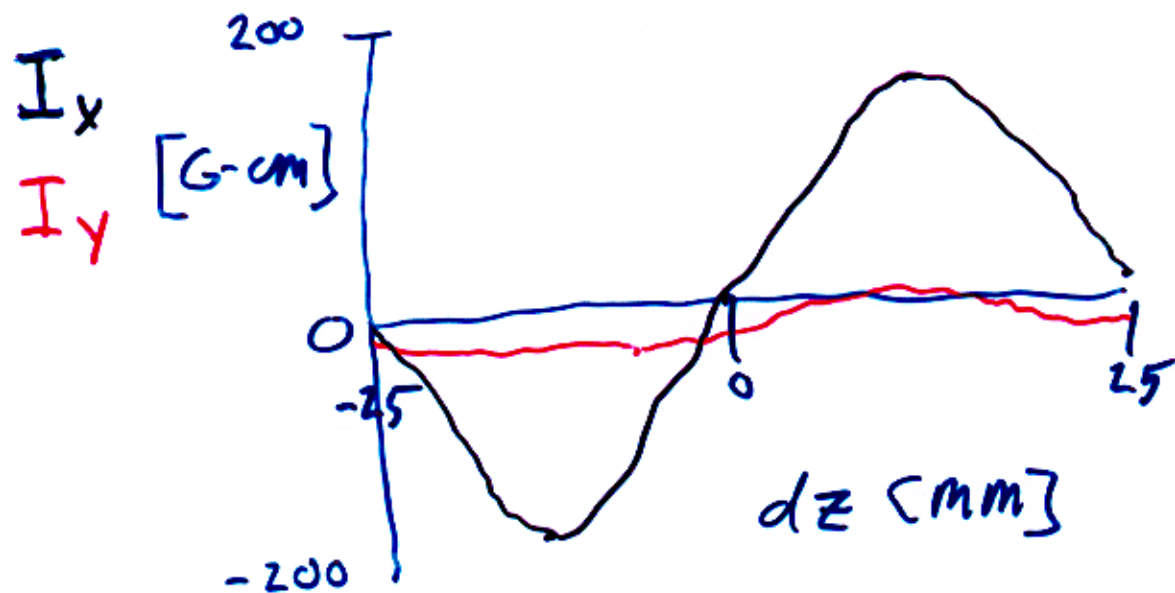
Spectral Quality



- 23 mm gap, $dz = 9$ mm
- $E_1 = 220$ eV, $E_3 = 660$ eV
- Field errors do not degrade polarization

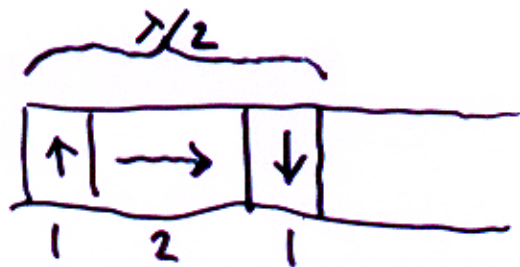
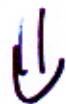
On-axis I_x, I_y a 14 mm gap

for axial Q1/Q3 shift $-\lambda \leq dz \leq \lambda$

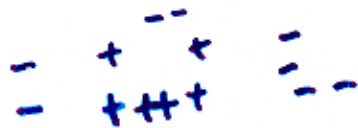


$$\lambda = 50$$

Kf/df end



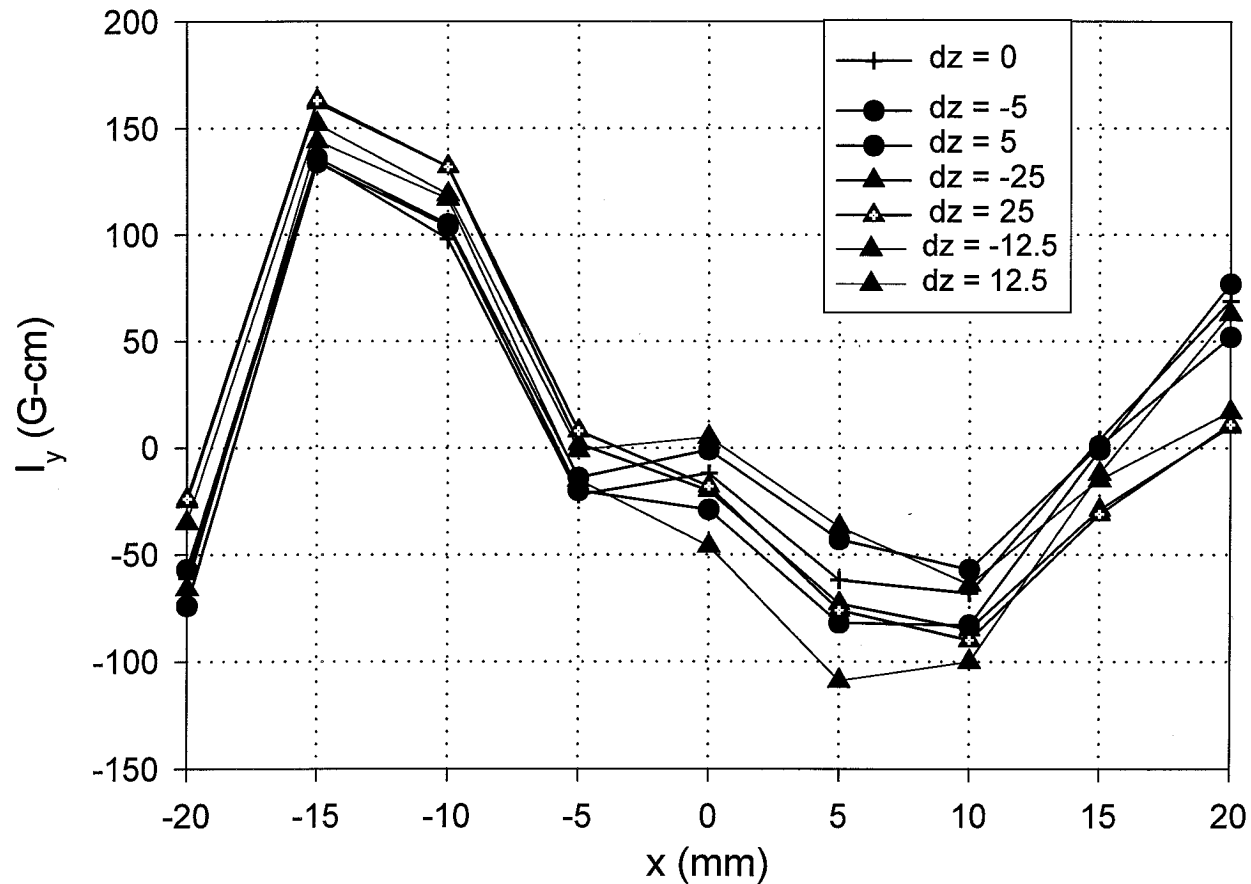
← this variation ramps up to Full Field most quickly



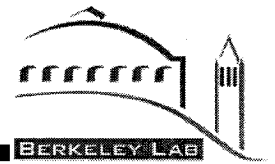
Integral Quality



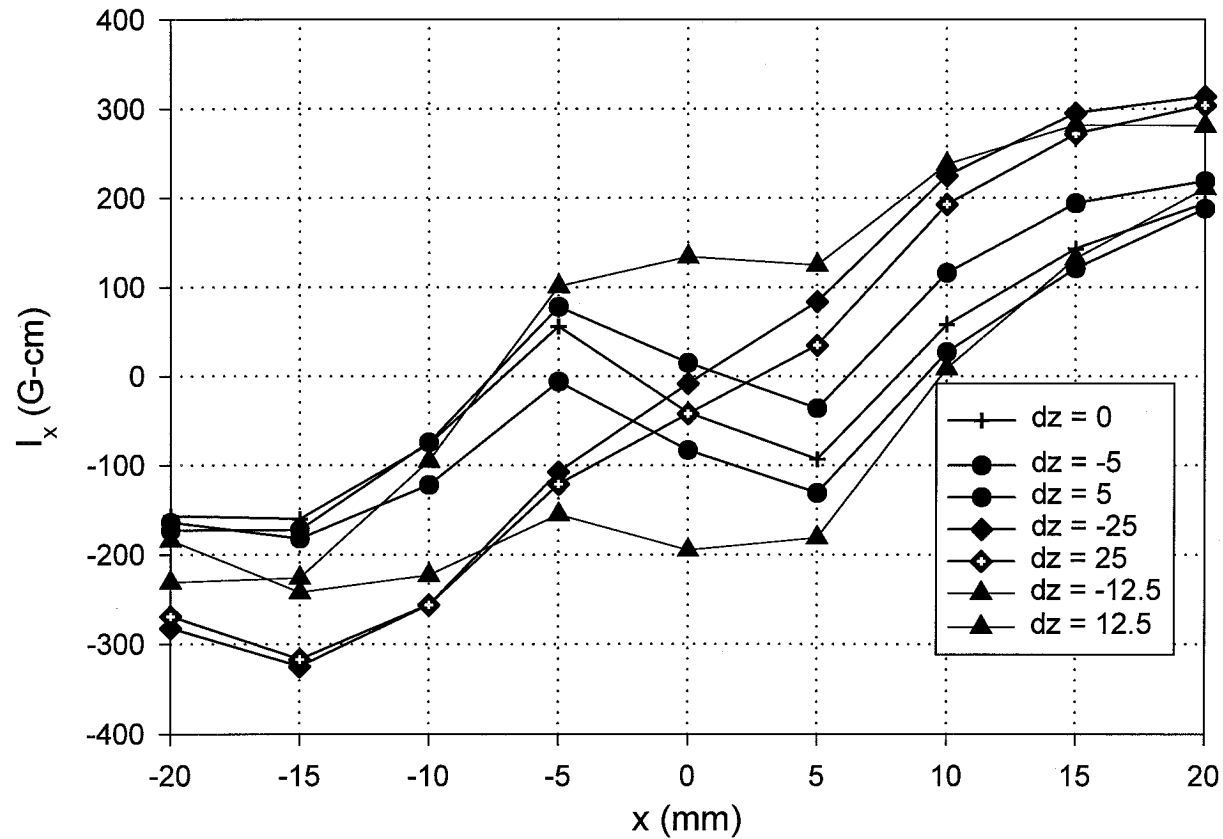
I_y vs x at $g=13.8\text{mm}$, for various dz



Integral Quality



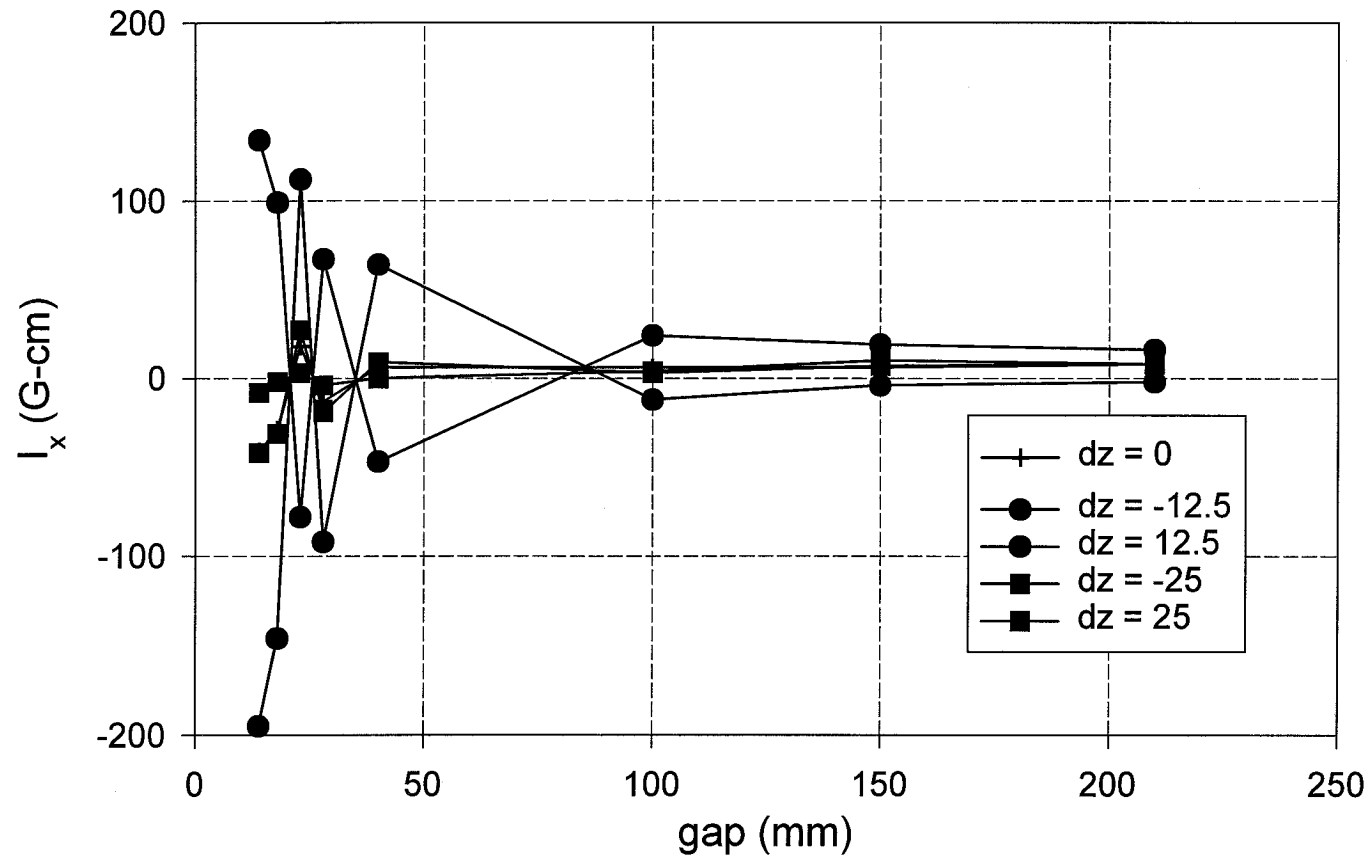
I_x vs x at $g=13.8\text{mm}$, for various dz



Integral Quality



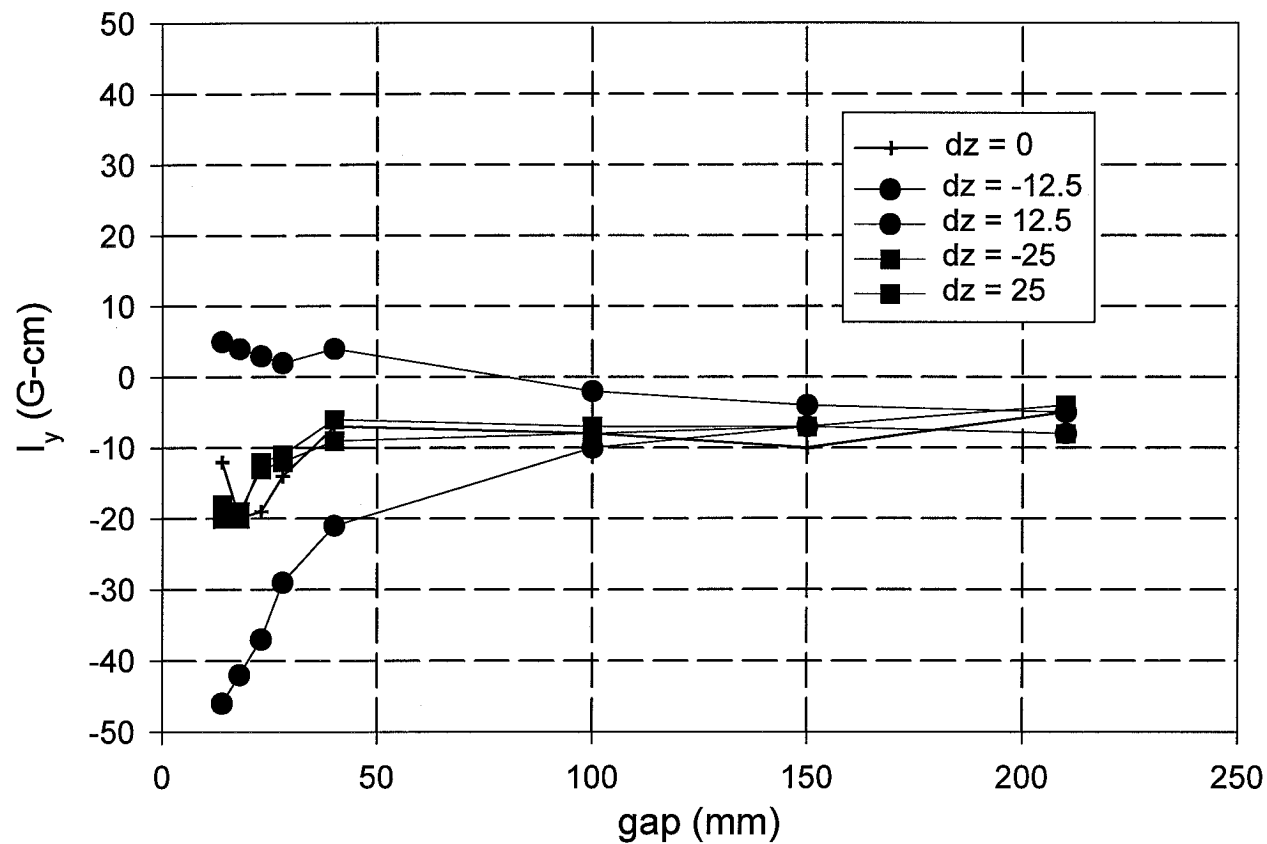
I_x vs. gap at $dz = 0$



Integral Quality



I_y vs. gap at $dz = 0$



Position Control



- **Requirements:**
 - **Gap repeatability:** $\pm 5 \mu\text{m}$
 - **Quadrant offset repeatability:** $\pm 1 \mu\text{m}$
 - **Forces change/reverse over range of dz**
 - F_x : +5262 lbs to -9528 lbs
 - F_y : -2982 lbs to +1728 lbs
- **Position repeatability limited by encoder resolution:**
 - **Gap:** $\pm 1 \mu\text{m}$
 - **Quadrant:** $\pm 0.25 \mu\text{m}$
 - **Settling time** $< 1.5 \text{ sec.}$