

Database for Accelerator Optics

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Abstract

The Automated Beam Steering and Shaping (ABSS) project aims to provide an automatic, generic and reliable software system to ensure the provision of high quality particle beams to users of an accelerator complex. An important component of this project is the access to validated reference data describing the different components installed in the machines, such as magnets as well as the optical and magnetic properties of all magnets. These properties are dependent on the type of particle, on the energy and on the destination of the beam. The data model must therefore be able to represent several particle beams along different trajectories through the same element. Furthermore, the database design must be sufficiently general to allow the description of the elements from a simple dipole to complex multipole magnets. For a given operation, the sequence of optics elements with the parameters appropriate to the type of beam must be extracted suitably from the data and passed as input to a beam optics program. This paper describes the problems encountered during the analysis, the resulting data schema and the software developed for data maintenance. Examples are given for the machines of the CERN PS complex.

1 Introduction

Databases for accelerators have been designed to fit the numerous requirements imposed by every machine complex machines [1]. The purpose of this database is to serve as a general reference document similar to an electronic parameter describing the input values needed for optics calculations. Much of the data describing the optics of the machines in the PS complex currently resides on paper and on files. A feasibility study [2] which took place during 1996, revealed the importance of providing a data model which is sufficiently general to describe all possible machine configurations. The aim of using a database is to provide a single source of data essential for the beam correction. These corrections are considered as perturbations of the reference machine documented in the database. The database is thus static and unaffected by accidental variations. This is a prerequisite for the reproducibility of an operation. An operation defines the list of components with which a particle beam, the component positions and the optics parameters by specifying the operation particle and momentum and the position and shape of the particle beam can be calculated and corrections made. The result is observed using beam measurement monitors.

The architecture of the database is developed around the concept of a machine operation. It accommodates the description of the complex machines used to make up a machine. Care has been taken to avoid any redundant data. The current system is restricted to the bending and focusing parameters of a complex of machines. The object management software, ACCIS (Accelerator Information System) which is used to describe, edit and browse the data is described.

2 Machine operation

A machine operation as defined here is the action of passing a beam from one part of a machine to another for a given purpose such as injection and acceleration. An example in the CERN context is the 5-tube extraction from the PS to the SPS. An operation requires a sequence of optics components, e.g. magnets and monitors, which are used to control the beam and the corresponding set of reference optics properties. An operation also requires the position of each component along the beam trajectory.

2.1 Beam path

The sequence of components is derived from a database object known as a beam path. A beam path describes the physical structure of a part of an accelerator or transfer line and may be used to describe more than one operation. An example is shown in Fig. 1. The beam path LInac Booster transfer line is made up of two transfer line sections, the LInac transfer line LT and the LInac Booster transfer line LTB. The LT section is made up, for example, of the dipole LTBHZ10, the focusing quadrupole LTQFN20 and defocusing quadrupole LTQDN22. The LTB section includes two quadrupoles and a beam position monitor LTUM A10.

To create a sequence of optics components a beam path is expanded into its component parts and then stripped of all non-optics components.

So that beam path parts can be reused in different operations, the parts of a beam path should not include elements at different branches of the sections. The branching of the LTA transfer line into the LT and LTE lines is represented as three sections. LTA includes the branching component LTBHZ10. This is shown in Fig. 2.

2.2 Topology

To position optics components along a beam path the

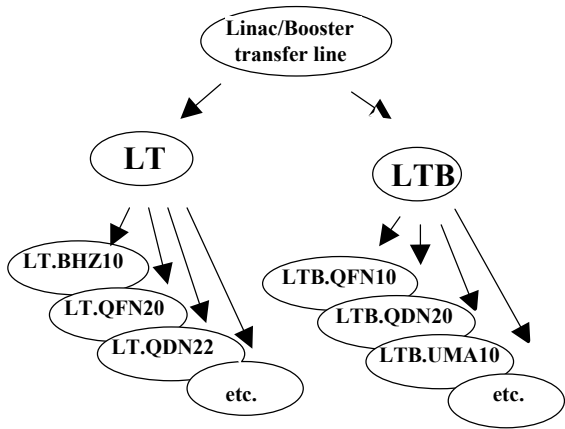


Fig1A Linac/Booster beam path

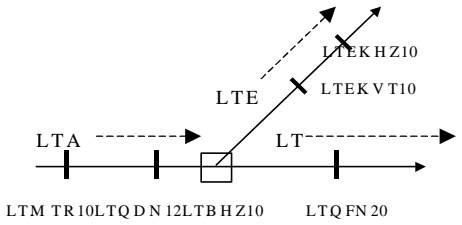


Fig2 LTA's position to LT and LTE

The displacement between the entry point of each element with respect to the parent object used is defined. Taking the example in Fig2 the pole LTB BHZ 10m is positioned relative to the parent machine part LT and LT relative to the beam path LT-LTB. From magnets the entry point indicates the start of the magnetic field.

2.3 Reference optics and correction

One of the corrections for steering and matching a beam is the daily task of the operation crew. A correction requires the solution of a linear system characterised by a matrix whose elements represent the effect of a unit correction at a magnet. For example, the data required for correcting the closed orbit in the PS ring includes the reference optics of one hundred magnets producing the main magnetic field as well as that of quadrupoles to set the transverse tunes. It also includes the horizontal and vertical pole correctors and the magnets whose main purpose is the displacement of the beam in a transverse plane at a given position in the ring. This data is then passed to a symbolic optics program [3] for team entry. A resulting correction to a field strength can be converted to a current variation given the measured magnetic rigidity in Tesla metres, that is the particle momentum electric charge momentum divided by the speed of light and calculated beam profiles.

The corrections are being expanded as steering and matching for the injection of particles from the Linac into the Booster and for the transfer between the Booster and PS, as well as for the closed orbit correction of the PS and the correction of the coherent transverse oscillations in the PS ring.

2.4 Component usage in an operation

The information describing how a component is to be used in an operation is called the usage. The term indicates whether a component is to be used for correction in the operation, and, if so, for what type of correction. When magnets have no other reference parameters magnet may have optics parameters. These are referenced by the usage. The relationship between the component and operation. If this relationship is removed, so is the usage. The magnet optics show every magnet may be referenced by other components and are therefore preserved in the database. A distinction is made between a component and any other magnet. A magnet may have optics parameters and may be used as a corrector. A next example of usage is shown in Fig3.

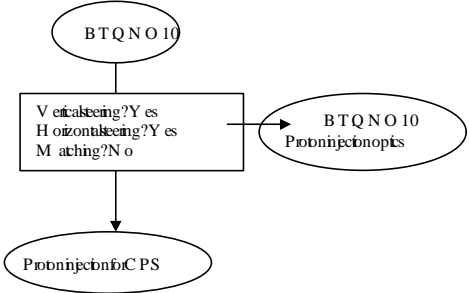


Fig3: A quadrupole in the reference optics used for both steering and matching during CPS injection.

3 Magnets

Magnets, both those used in the PS today and those foreseen for LHC [4] can be complex. A magnet may be supplied by a current passing through more than one coil. These same power sources may supply several coils. A magnet may be operating in an unsaturated domain regime depending on the current being supplied. Coils may be used to correct the reference magnetic field in order to adjust the tune and chromaticity as well as compensate irregularities in the magnetic field. Correction magnets may themselves have a nominal field. When a magnet is made up of superposed coils the magnetic field may overlap. A coil of a magnet may provide a field having a polarity, such as a dipole or quadrupole, or a field which is made up of several components.

CERN PS magnets are used as an example. Each is made up of four sectors, each sector is composed of several coils. The main coil and correction coils. The main coil defines the

nominal magnetic field of the beam machine (no correctors included) is a combined function coil provides both bending and focusing fields. The correction coils include a background winding coil with quadrupole and sextupole components used at high energy in order to compensate saturation effects and to adjust the natural chromaticities of the machine. A special bore winding quadrupole component is used at high energy to control the transverse tunes of the machine.

Beam splitting magnets may act in a different way on different particle beams. The PS booster vertical distribution magnet consists of six dipoles located in the same vertical plane but in sequence on the injection line (Fig 4).

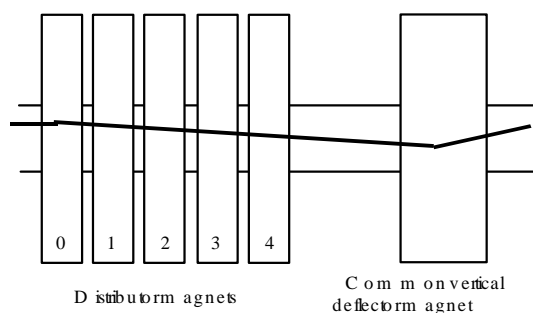


Fig 4: The Distributing magnet consists of five dipoles positioned in the same vertical plane but in sequence on the injection line. The fifth magnet is a combinatorial deflection magnet.

Each of the five first dipoles, so called distributing magnets, have one single nominal bending angle. The sixth magnet serves as a combinatorial deflection magnet with one single bending angle. To get the best PSB ring, only four distributing magnets are active and to get the best four of the distributing magnets are active. In both cases the combinatorial deflection magnet is at its nominal value. Consequently, the database has in addition to dealing with non-active magnets to deal with magnets with single nominal bending angle but with different edge-up and edge-down angles.

3.1 Magnet elements

In order to cope with the definition of composite magnets in the database, the concept of magnet element has been introduced. A magnet element provides a magnetic field generated by a current passing through a single coil by no current at all is a permanent magnet. For example, in the LHC magnets composed of three magnet elements: the main dipole, the correction sextupole and the correction decapole. Each coil is connected to a single power source, supplied by one or more power supplies. A composite magnet may be made up of several sequentially superposed magnet elements with totally or partially overlapping fields. Magnet fields may have as single components such as a

dipole or quadrupole component may be described by several field components. Eight components are currently included in the database. The optical field strengths used for calibration are given in part 6 and momentum independent units which reduces the number of operations to be defined to a minimum. The justification for the choice of field model parameters is described below.

3.2 Magnet field model

The field model is the one of a hard edge magnet with a transverse field whose Taylor expansion is truncated at the octupole term. The field is thus characterised by dipole, quadrupole and sextupole coefficients. Each coefficient has an upright and a skew component so that the field is determined by eight independent coefficients. The field coefficients are those measured in the laboratory with the reference system of the measurement bench. In the case of ion magnets the field is a very good precision upright and the skew components are negligible. In superconducting magnets, the skew components have to be considered. In a beam machine and especially in a transfer magnet, the orientation may be different from its orientation in the laboratory longitudinal axis. O_z always also coincides with the beam orbit and the only angle which matters in practice is the angle about O_z called the *tilt* of the magnet. It is a special attribute of a magnet element.

The Lorentz force exerted by the magnetic field on a particle is proportional to the field integrated over the magnetic length l of the element to the particle electric charge and inversely proportional to the particle momentum. To each field component corresponds an optical coefficient namely the particle deflection, the integrated focusing strength Kl , measured in m^{-2} and the first and second radial derivatives of Kl as well as the case for the field there are upright and skew optical coefficients.

A correction is first expressed in physical units such as radians for deflection, m^{-2} for a beam envelope or rate shift. The physical unit is converted into a current or a voltage via a calibration coefficient which is defined as the derivative of some field coefficient with respect to the current (or the voltage). With this definition, the calibration coefficient may be a function of the current as it happens when a magnet operates in a saturated regime. Varying the calibration coefficient by the magnet rigidity achieves the transformation of physical to engineering units.

3.3 Calibration

In the database, a magnet element is described by a magnetic field which has a magnetic length and field measurement points taken at different currents or voltages for each of the eight upright and skew components. A magnetic field description may be shared by many magnet elements such as those in the main magnets of the CERN PS. Fig. 5 shows the definition of calibration data for a magnet element.

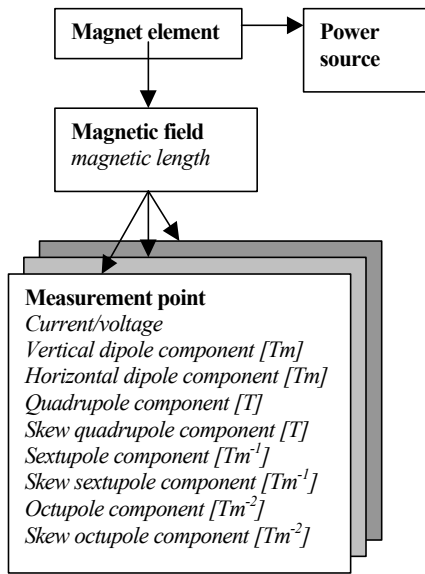


Fig5: The database definition of a magnet element referenced by a magnet element

3.4 Reference optics

A magnet element can be defined and the angle of the beam can be defined in milliradians. The magnet optics parameters include the vertical and horizontal bending angles given in milliradians, the upright and skew quadrupole strengths in m^{-2} , sextupole strengths in m^{-3} and octupole strengths in m^{-4} . They also include the optics type, currently dipole or quadrupole, and the angles of the normal to the entry and exit magnet faces, edge up-stream and edge down-stream, and the trajectory length. A set of magnet optics parameters may be used in more than one operation, but only one set may be referenced per operation. The model summary is listed in Fig6.

4 Database functionality

The data model may be extended to reference data stored in ORACLE tables maintained outside the ABS system, such as the PS control system [5] and survey databases.

ABS specific object methods have been developed to pass the data to the optics program where it can be used to generate the reference optics and to maintain the data for an operation. These methods also provide lists of positions of correctors and monitors as well as connection data and power supply names to application programs [6].

The optics program requires a formatted list of optics elements in the input file in order to calculate a matrix to describe the normal optics as well as lists of correctors and monitors with their positions in order to

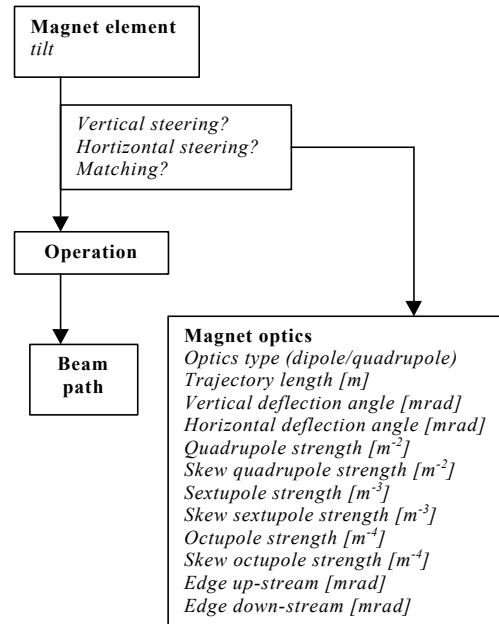


Fig6: The description of the optics of a magnet element for an operation.

generate the data describing a beam optics channel the operation beam path would first be expanded into its component elements. The resulting data is then stripped of those elements which are not used in the operation. The channel is assumed to start and end at the beginning and end of the beam path. The position of each element can be derived from the displacement of each element given relative to the parent machine part in the beam path structure. The operation optics of each magnet element is treated: positions and distances calculated, the data formatted and then sent to the symbolic optics program. Lists of correctors and monitors are included in the expanded information with their position relative to the start of the beam path. In order to import this data into the symbolic optics program, the user has to type a simple command and followed by the operation and type of steering correction he wishes to treat.

5 Data management software (ACCIS)

The software used to manage the data is ACCIS (Accelerator Information System) a generic object management system developed at CERN. The data repository is the relational database management system ORACLE. The software provides tools to define object classes as well as a basic set of object management methods on top of which methods particular to the ABS can be built. Once the object classes have been defined the user can immediately start to enter data without further software development using a generic format and screen for data entry (Fig7).

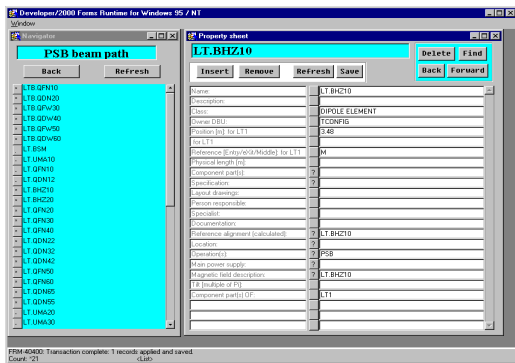


Fig7: The ORACLE Form slatent and maintenance screen.

ACCIS includes a WEB browser for interrogating the data. A next page of a WEB page is shown in Figure 8. The browser has the WEB browser and few buttons on a reference field, a new page will be displayed. The ACCIS WEB pages show even dynamically created from data in the database using procedures also stored in the database using the ORACLE WebServer facilities. Therefore as soon as the data is changed, the modification can be seen using the browser.

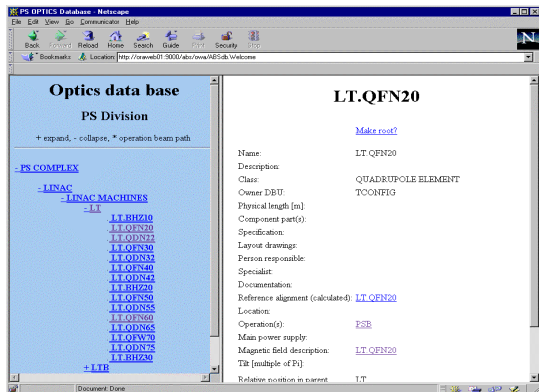


Fig8: The Optics database WEB browser.

6 Evolution and conclusion

The main aim of the Accelerator Optics Database is to fully describe the machine operations in an accelerator complex and to import the data into a symbolic optics program for generating correction matrices. The database must also provide lists of correctors and monitors and calibration data to the application software. The objectives have been achieved for the Linac to Booster transfer in the correction information for the transfer. The magnet

element concept has also been verified by using the database to describe the more complex CPS and LHC magnets. Since the testing of the system has begun, anomalies have been detected arising from incorrect reference parameters which have subsequently been corrected. The Accelerator Optics Database can be used to verify the correctness of the data.

The ACCIS software allows the definition of further descriptive properties without the necessity of modifying the software. There is no need to restrict the data entered to that required for the ABS project. Indeed apart from the structural decomposition of an accelerator transfer line, the database also includes specification data that provides supplementary information to operators. This data can also be seen using the WEB browser and is being increasingly interrogated. This information could be eventually extended to include a complete documentation of the PS complex.

The data entered into the earlier version of the database has been successfully migrated into the new object model. The next step is to complete and check the description of the remainder of the PS complex operations.

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